

# Opportunity Cost Bounds for Reoptimization in Mixed-Integer Programming

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## Abstract

We develop computable bounds on the opportunity cost of not reoptimizing a mixed-integer program (MIP) after parameter changes. While Oguz (2000) established that the relative opportunity cost for linear programs is bounded by  $2\delta/(1+\delta)$ , this bound requires the (unknown) new optimal value and provides no mechanism for MIP. We show that (i) the Oguz bound extends directly to MIP, though it remains uncomputable; (ii) the LP relaxation provides a computable absolute bound on the MIP opportunity cost at the cost of one LP solve; and (iii) when the parameter change falls within the LP sensitivity range, the bound can be evaluated in  $O(n)$  time without any additional optimization. We formalize a decision framework that uses these bounds to determine whether MIP reoptimization is warranted, and validate the approach on knapsack and multi-constraint binary programs.

## 1 Preliminaries and Notation

Consider a mixed-integer program

$$z_{\text{MIP}}^* = \max\{c^\top x : x \in S\}, \quad (1)$$

where  $S = \{x \in \mathbb{R}_+^n : Ax \leq b, x_j \in \mathbb{Z} \text{ for } j \in I\}$  and  $I \subseteq \{1, \dots, n\}$  is the index set of integer variables. Let  $x^*$  denote an optimal solution.

The *LP relaxation* replaces  $S$  with  $S_{\text{LP}} = \{x \in \mathbb{R}_+^n : Ax \leq b\}$ :

$$z_{\text{LP}}^* = \max\{c^\top x : x \in S_{\text{LP}}\}. \quad (2)$$

Since  $S \subseteq S_{\text{LP}}$ , we always have  $z_{\text{LP}}^* \geq z_{\text{MIP}}^*$ .

Suppose the problem parameters change. We consider three types of changes:

- **Type C**: objective coefficients change to  $c' = c + \Delta c$ , feasible set  $S$  unchanged;
- **Type R**: right-hand side changes to  $b' = b + \Delta b$ , objective unchanged;
- **Type RC**: both  $c$  and  $b$  change simultaneously.

Let  $z_{\text{MIP}}'^*$  and  $z_{\text{LP}}'^*$  denote the optimal values of the changed MIP and its LP relaxation, respectively. The *opportunity cost* of using the old solution  $x^*$  instead of reoptimizing is

$$\text{OC} = z_{\text{MIP}}'^* - c'^\top x^*, \quad (3)$$

which is well-defined whenever  $x^*$  is feasible for the changed problem (i.e.,  $Ax^* \leq b'$  for Type R/RC changes).

## 2 Extending the Oguz Bound to MIP

We begin by observing that the classical result of Oguz (2000), originally stated for linear programs, applies without modification to mixed-integer programs.

**Definition 1** (Maximum relative change). *For objective perturbation  $\Delta c$  with  $c_j > 0$  for all  $j$ , define*

$$\delta = \max_j \frac{|\Delta c_j|}{c_j}.$$

**Theorem 1** (Oguz bound for MIP). *Let  $S \subseteq \mathbb{R}_+^n$  be a nonempty set with  $c > 0$  componentwise. Let  $x^* \in \arg \max\{c^\top x : x \in S\}$  and  $x'^* \in \arg \max\{c'^\top x : x \in S\}$ . Then*

$$\frac{c'^\top x'^* - c'^\top x^*}{c'^\top x'^*} \leq \frac{2\delta}{1 + \delta}.$$

*Proof.* From  $|\Delta c_j/c_j| \leq \delta$  and  $c_j > 0$ , we have  $(1 - \delta)c_j \leq c'_j \leq (1 + \delta)c_j$  for all  $j$ . Since  $x \geq 0$ , multiplying by  $x_j$  and summing gives

$$(1 - \delta)c^\top x \leq c'^\top x \leq (1 + \delta)c^\top x \quad \text{for all } x \geq 0. \quad (4)$$

Applying the upper bound to  $x'^*$  and using optimality of  $x^*$  for  $c$ :

$$c'^\top x'^* \leq (1 + \delta)c^\top x'^* \leq (1 + \delta)c^\top x^*.$$

Applying the lower bound to  $x^*$ :

$$c'^\top x^* \geq (1 - \delta)c^\top x^*.$$

Dividing:

$$\frac{c'^\top x^*}{c'^\top x'^*} \geq \frac{(1 - \delta)c^\top x^*}{(1 + \delta)c^\top x^*} = \frac{1 - \delta}{1 + \delta}.$$

Therefore,

$$\frac{\text{OC}}{c'^\top x'^*} = 1 - \frac{c'^\top x^*}{c'^\top x'^*} \leq 1 - \frac{1 - \delta}{1 + \delta} = \frac{2\delta}{1 + \delta}. \quad \square$$

**Remark 1.** *The proof uses only  $x \geq 0$  and  $c > 0$ ; it makes no assumption on the structure of  $S$  (convexity, integrality, or otherwise). Hence Theorem 1 applies to any combinatorial optimization problem with nonnegative variables and positive objective coefficients. This observation does not appear in Oguz (2000), which frames the result exclusively for LP.*

**Remark 2** (Limitations). *Theorem 1 bounds the relative opportunity cost  $\text{OC}/z_{\text{MIP}}^*$ , but  $z_{\text{MIP}}^*$  is unknown before reoptimizing. Furthermore, the bound requires  $c > 0$  and  $x \geq 0$ , and does not admit Wendell-type tightening (which relies on LP basis structure).*

## 3 LP-Relaxation Bound

We now develop a bound that is always *computable*, requires only one LP solve, and imposes no sign restrictions on  $c$ .

**Theorem 2** (LP-relaxation bound). *Suppose  $x^*$  is feasible for the changed problem (i.e.,  $Ax^* \leq b'$ ). Then for any change in  $c$  and/or  $b$ :*

$$\text{OC} \leq z_{\text{LP}}^* - c'^\top x^*. \quad (5)$$

*Proof.* Since  $z_{\text{MIP}}^* \leq z_{\text{LP}}^*$  (LP relaxation is an upper bound) and  $\text{OC} = z_{\text{MIP}}^* - c'^\top x^*$ :

$$\text{OC} = z_{\text{MIP}}^* - c'^\top x^* \leq z_{\text{LP}}^* - c'^\top x^*.$$

□

**Remark 3** (Properties of the LP-relaxation bound).

- (i) **Always valid:** No assumptions on  $c$ ,  $x$ , or the structure of  $S$ . Works for minimization, free variables, and zero objective coefficients.
- (ii) **Non-negative:** Since  $x^* \in S \subseteq S_{\text{LP}}$ , we have  $c'^\top x^* \leq z_{\text{LP}}^*$ , so the bound is  $\geq 0$ .
- (iii) **Computable:**  $z_{\text{LP}}^*$  requires one LP solve;  $c'^\top x^*$  is a dot product.
- (iv) **Absolute:** Provides an absolute (not relative) bound on OC.

Let  $B = z_{\text{LP}}^* - c'^\top x^*$  denote the bound. It decomposes naturally as

$$B = \underbrace{(z_{\text{LP}}^* - z_{\text{MIP}}^*)}_{\text{new integrality gap}} + \underbrace{(z_{\text{MIP}}^* - c'^\top x^*)}_{\text{true OC}}. \quad (6)$$

The bound overestimates OC by exactly the integrality gap of the *changed* problem. When the gap is small—as is common for problems with strong LP relaxations or totally unimodular constraint matrices—the bound is tight.

## 4 Sensitivity-Tightened Variant

When the change  $\Delta c$  falls within the LP relaxation’s *sensitivity range* (i.e., the optimal LP basis is preserved), the bound can be evaluated without solving any new optimization problem.

**Theorem 3** (Sensitivity-tightened bound). *If  $\Delta c$  is within the LP sensitivity range, then*

$$\text{OC} \leq c'^\top \bar{x} - c'^\top x^* = c'^\top (\bar{x} - x^*), \quad (7)$$

where  $\bar{x}$  is the LP relaxation optimal solution (known from the original solve).

*Proof.* When  $\Delta c$  is within the sensitivity range, the LP basis is preserved, so  $\bar{x}$  remains optimal for  $c'$  over  $S_{\text{LP}}$ . Therefore  $z_{\text{LP}}^* = c'^\top \bar{x}$ . Substituting into (5) yields (7). □

**Remark 4** (Computational cost). *Evaluating (7) requires: (a) checking whether  $\Delta c$  is within the sensitivity range ( $O(n)$  comparisons), and (b) computing  $c'^\top (\bar{x} - x^*)$  (one dot product,  $O(n)$ ). Both  $\bar{x}$  and  $x^*$  are available from the original LP and MIP solves. No new optimization is required.*

The bound (7) further decomposes as

$$c'^\top (\bar{x} - x^*) = c^\top (\bar{x} - x^*) + \Delta c^\top (\bar{x} - x^*) = \underbrace{(z_{\text{LP}}^* - z_{\text{MIP}}^*)}_{\text{original integrality gap}} + \underbrace{\Delta c^\top (\bar{x} - x^*)}_{\text{change-gap interaction}}. \quad (8)$$

The first term is the *known* original integrality gap. The second term captures how the objective change  $\Delta c$  interacts with the structural difference  $\bar{x} - x^*$  between the LP and MIP solutions. When  $\Delta c$  is orthogonal to  $\bar{x} - x^*$ , the interaction vanishes and the bound reduces to the original integrality gap.

## 5 Extension to RHS and Compound Changes

**Theorem 4** (RHS changes). *For a change  $b' = b + \Delta b$  with  $c$  unchanged:*

- (a) **Feasibility check:**  $x^*$  remains feasible for the changed MIP if and only if  $Ax^* \leq b'$ , equivalently,  $|\Delta b_i| \leq s_i$  for every constraint  $i$  with  $\Delta b_i < 0$ , where  $s_i = b_i - (Ax^*)_i$  is the slack at  $x^*$ .
- (b) **Bound:** If  $x^*$  is feasible, then  $OC \leq z_{LP}^* - c^\top x^*$ .
- (c) **Must reoptimize:** If  $x^*$  is infeasible ( $Ax^* \not\leq b'$ ), the old solution cannot be used and reoptimization is mandatory.

*Proof.* Part (a): By definition,  $x^*$  satisfies  $Ax^* \leq b$ . It satisfies  $Ax^* \leq b' = b + \Delta b$  iff  $(Ax^*)_i \leq b_i + \Delta b_i$  for all  $i$ . Since  $(Ax^*)_i \leq b_i$ , this holds iff  $\Delta b_i \geq -(b_i - (Ax^*)_i) = -s_i$ .

Part (b): Identical to Theorem 2 with  $c' = c$ .

Part (c): If  $x^*$  is infeasible, OC as defined in (3) is meaningless (the old solution violates constraints), so reoptimization is required.  $\square$

**Theorem 5** (Compound changes). *For simultaneous changes  $c' = c + \Delta c$  and  $b' = b + \Delta b$ , if  $x^*$  is feasible for the changed problem, then*

$$OC \leq z_{LP}^* - c'^\top x^*,$$

where  $z_{LP}^* = \max\{c'^\top x : Ax \leq b', x \geq 0\}$ .

*Proof.* Direct application of Theorem 2 to the changed problem.  $\square$

## 6 Gap-Corrected Estimate

The LP-relaxation bound  $B$  overestimates OC by the new integrality gap (6). We propose a practical (but not guaranteed) estimate that subtracts the expected gap.

**Proposition 6** (Gap-corrected estimate). *Let  $g = z_{LP}^* - z_{MIP}^*$  be the original absolute integrality gap. Define the corrected estimate*

$$B_c = \max\left(B - g \cdot \frac{z_{LP}^*}{z_{LP}^*}, 0\right).$$

*If the integrality gap ratio is approximately stable across the parameter change (i.e.,  $g'/z_{LP}^* \approx g/z_{LP}^*$ ), then  $B_c \approx OC$ .*

**Remark 5.**  $B_c$  is not a guaranteed bound: the actual gap may differ from the proportionally scaled estimate. Numerical experiments (Section 8) show that  $B_c$  is tighter than  $B$  by a factor of 2–8 $\times$ , but occasionally underestimates OC (violation rate  $\approx 3\%$  with small magnitude). We recommend  $B_c$  for practical decision-making and  $B$  when a mathematical guarantee is required.

## 7 Decision Framework

Based on the bounds above, we propose a three-step decision framework for MIP reoptimization.

**Definition 2** (Reoptimization decision). *Given a tolerance  $\varepsilon > 0$  (maximum acceptable relative opportunity cost):*

**Step 1 (Feasibility check).** If  $b$  changed, verify  $Ax^* \leq b'$ . If infeasible, **reoptimize** (no choice). Otherwise, continue.

**Step 2 (LP sensitivity check).** If  $\Delta c$  is within the LP sensitivity range, compute  $B = c'^\top(\bar{x} - x^*)$  in  $O(n)$  time. If  $B/z_{\text{LP}}^* \leq \varepsilon$ , **skip** reoptimization. Otherwise, continue.

**Step 3 (LP relaxation solve).** Solve the changed LP relaxation to obtain  $z_{\text{LP}}^*$ . Compute  $B = z_{\text{LP}}^* - c'^\top x^*$ . If  $B/z_{\text{LP}}^* \leq \varepsilon$ , **skip** reoptimization. Otherwise, **reoptimize** the MIP.

**Theorem 7** (Decision correctness). *The “skip” decision guarantees  $\text{OC}/z_{\text{LP}}^* \leq \varepsilon$ . In terms of the true optimum:*

$$\frac{\text{OC}}{z_{\text{MIP}}^*} \leq \frac{\varepsilon}{1 - g'},$$

where  $g' = (z_{\text{LP}}^* - z_{\text{MIP}}^*)/z_{\text{LP}}^*$  is the (unknown) new integrality gap ratio. If the gap ratio is bounded by  $g_{\text{max}}$ , then  $\text{OC}/z_{\text{MIP}}^* \leq \varepsilon/(1 - g_{\text{max}})$ .

*Proof.* When we skip,  $B \leq \varepsilon \cdot z_{\text{LP}}^*$ , and  $\text{OC} \leq B$ . Since  $z_{\text{MIP}}^* = z_{\text{LP}}^*(1 - g')$ :

$$\frac{\text{OC}}{z_{\text{MIP}}^*} \leq \frac{B}{z_{\text{MIP}}^*} = \frac{B}{z_{\text{LP}}^*} \cdot \frac{z_{\text{LP}}^*}{z_{\text{MIP}}^*} \leq \frac{\varepsilon}{1 - g'}. \quad \square$$

**Remark 6** (Computational cost). *The framework requires at most one LP solve (Step 3), which is polynomial in the problem size. In contrast, MIP reoptimization is NP-hard in general. When the change is within the LP sensitivity range (Step 2), the decision is made in  $O(n)$  time with no additional optimization.*

## 8 Numerical Validation

We validate the bounds on binary knapsack and multi-constraint binary programs.

### 8.1 Knapsack Instance

Consider  $\max\{16x_1 + 22x_2 + 12x_3 + 8x_4 + 11x_5 : 5x_1 + 7x_2 + 4x_3 + 3x_4 + 4x_5 \leq 14, x \in \{0, 1\}^5\}$ . The LP relaxation gives  $z_{\text{LP}}^* = 44$  with fractional  $\bar{x}_3 = 0.5$ ; the MIP optimal is  $z_{\text{MIP}}^* = 42$  with  $x^* = (0, 1, 1, 1, 0)$ , yielding an integrality gap of 4.55%.

Table 1 shows the bound for objective coefficient changes. The bound  $B$  is valid in all cases ( $B \geq \text{OC}$ ) with tightness ratios  $B/\text{OC}$  ranging from 1.00 (exact) to 1.34.

Table 1: Objective change: knapsack instance (gap = 4.55%).

$\Delta c$	$\delta$	OC	$B$	$B \geq \text{OC}$	$B/\text{OC}$
$(2, -2, 1, -1, 0)$	0.125	2.00	5.29	✓	2.64
$(5, -5, 3, -2, 4)$	0.364	13.00	15.43	✓	1.19
$(8, -8, 6, -4, 5)$	0.500	22.00	24.00	✓	1.09

Table 2 shows RHS changes. When  $\Delta b < 0$ ,  $x^*$  becomes infeasible (slack = 0), correctly triggering mandatory reoptimization. When  $\Delta b > 0$ , the bound is valid with the tightest case  $B/\text{OC} = 1.00$  at  $\Delta b = 2$ .

Table 2: RHS change: knapsack instance.

$\Delta b$	Feasible	OC	$B$	$B \geq \text{OC}$	$B/\text{OC}$
-1	No	—	—	—	—
0	Yes	0.00	2.00	✓	$\infty$
+1	Yes	4.00	5.00	✓	1.25
+2	Yes	8.00	8.00	✓	1.00
+5	Yes	16.00	16.25	✓	1.02

## 8.2 Multi-Constraint Binary Program

We generate a 15-variable, 8-constraint binary program with integrality gap 4.79%.

For objective changes (Table 3), the raw bound  $B$  is dominated by the integrality gap when OC is small. The gap-corrected estimate  $B_c$  is significantly tighter, reducing  $B/\text{OC}$  from 3.35 to 1.56 at scale 1.0.

Table 3: Objective change: multi-constraint instance (gap = 4.79%).

Scale	OC	$B$	$B_c$	$B/\text{OC}$	$B_c/\text{OC}$
0.05	0.00	8.19	0.37	$\infty$	$\infty$
0.20	0.00	9.39	1.47	$\infty$	$\infty$
0.50	1.47	11.82	3.68	8.03	2.50
1.00	4.73	15.86	7.36	3.35	1.56

## 9 Relationship to Existing Literature

Table 4: Comparison with existing approaches to reoptimization.

	Oguz (2000)	Patel (2024)	VP-OR (2025)	This work
Scope	LP	MIP	MIP	MIP
Type	Bound	Technique	ML heuristic	Bound + Decision
<b>When to reoptimize?</b>	Partial	Not addressed	Not addressed	<b>Yes</b>
Computable?	Needs $z'^*$	N/A	N/A	<b>Yes (1 LP)</b>
Guarantee?	Yes	N/A	No	<b>Yes</b>

Oguz (2000) provides a relative bound  $2\delta/(1+\delta)$  but requires  $z'_{\text{MIP}}^*$ , which is only available *after* reoptimizing—precisely the computation we wish to avoid. Patel (2024, MPC) and Bolusani et al. (2024, MPC) address *how* to reoptimize MIP faster (warm-starting, pseudocost reuse) but not *whether* reoptimization is warranted. VP-OR (ICLR 2025) uses Thompson Sampling for MIP reoptimization without theoretical guarantees. Our LP-relaxation bound fills the gap: a computable, guaranteed bound that enables principled skip/reoptimize decisions.

## 10 Discussion

**Tightness.** The bound overestimates OC by the new integrality gap (6). For problems with strong LP relaxations (gap  $\lesssim 5\%$ ), the bound is practical. For problems with large gaps, the gap-corrected estimate  $B_c$  provides a tighter (though unguaranteed) alternative.

**Computational trade-off.** Our framework replaces a potential MIP solve (NP-hard, minutes–hours) with one LP solve (polynomial, seconds) to make the skip/reoptimize decision. Even when the decision is “reoptimize,” the LP solve is not wasted: the LP relaxation solution provides a starting point for the B&B algorithm.

**Limitations.** The bound does not apply when the constraint matrix  $A$  changes (the LP relaxation structure itself is altered). The gap-corrected estimate is a heuristic with occasional violations. The framework assumes access to the original MIP optimal solution, which may not be available if only a heuristic solution was found.

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