

Brahe: A Modern Astrodynamics Library for Research and Engineering Applications

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Summary

`brahe` is a modern astrodynamics dynamics library for research and engineering applications. The representation and prediction of satellite motion is the fundamental problem of astrodynamics. The motion of celestial bodies has been studied for centuries with initial equations of motion dating back to Kepler (1619) and Newton (1687). Current research and applications in space situational awareness, satellite task planning, and space mission operations require accurate and efficient numerical tools to perform coordinate transformations, model perturbations, and propagate orbits. `brahe` incorporates the latest conventions and models for time systems and reference frame transformations from the International Astronomical Union (IAU) (Hohenkerk, 2017) and International Earth Rotation and Reference Systems Service (IERS) (Petit & Luzum, 2010). It implements force models for Earth-orbiting satellites including atmospheric drag, solar radiation pressure, and third-body perturbations from the Sun and Moon (Montenbruck & Gill, 2000; D. A. Vallado, 2001). It also provides standard orbit propagation algorithms, including the Simplified General Perturbations (SGP) Model (D. Vallado et al., 2006). Finally, it implements recent algorithms for fast, parallelized computation of ground station and imaging-target visibility (Eddy & Kochenderfer, 2021), a foundational problem in satellite scheduling and mission planning.

With `brahe`, predicting upcoming satellite passes over ground stations or imaging targets can be accomplished in seconds and three lines of code.

```
import brahe as bh
bh.initialize_eop()
passes = bh.location_accesses(
    bh.PointLocation(-122.4194, 37.7749, 0.0), # San Francisco
    bh.celestrak.get_tle_by_id_as_propagator(25544, 60.0, "active"), # ISS
    bh.Epoch.now(),
    bh.Epoch.now() + 24 * 3600.0, # Next 24 hours
    bh.ElevationConstraint(min_elevation_deg=10.0)
)
```

`brahe` allows users to quickly access Two-Line Element (TLE) data from Celestrak (Kelso, T. S., 2025) and propagate orbits using the SGP4 dynamics model. This can be used to perform space situational awareness tasks such as predicting the orbits of all Starlink satellites over the next 24 hours.

```
import brahe as bh
bh.initialize_eop()
starlink = bh.datasets.celestrak.get_tles_as_propagators("starlink", 60.0)
bh.par_propagate_to(starlink, bh.Epoch.now() + 86400.0) # Predict next 24 hours
```

The above routine can propagate orbits for all ~9000 Starlink satellites in approximately 1 minute 30 seconds on an M1 Max MacBook Pro with 10 cores and 64 GB RAM. Finally, the package provides direct, easy-to-use functions for low-level astrodynamics routines such as Keplerian to Cartesian state conversions and reference frame transformations.

```

53
54
55 import brahe as bh
56 import numpy as np
57
58 # Initialize Earth Orientation Parameter data
59 bh.initialize_eop()
60
61 # Define orbital elements
62 a = bh.constants.R_EARTH + 700e3 # Semi-major axis in meters (700 km altitude)
63 e = 0.001 # Eccentricity
64 i = 98.7 # Inclination in radians
65 raan = 15.0 # Right Ascension of Ascending Node in radians
66 arg_periapsis = 30.0 # Argument of Periapsis in radians
67 mean_anomaly = 45.0 # Mean Anomaly
68 state_kep = np.array([a, e, i, raan, arg_periapsis, mean_anomaly])
69
70 # Convert Keplerian state to ECI coordinates
71 state_eci = bh.state_koe_to_eci(state_kep, bh.AngleFormat.DEGREES)
72
73 # Define a time epoch
74 epoch = bh.Epoch(2024, 6, 1, 12, 0, 0.0, time_system=bh.TimeSystem.UTC)
75
76 # Convert ECI coordinates to ECEF coordinates at the given epoch
77 state_ecef = bh.state_eci_to_ecef(epoch, state_eci)
78
79 # Convert back from ECEF to ECI coordinates
80 state_eci_2 = bh.state_ecef_to_eci(epoch, state_ecef)
81
82 # Convert back from ECI to Keplerian elements
83 state_kep_2 = bh.state_eci_to_koe(state_eci_2, bh.AngleFormat.DEGREES)
84
85

```

Another example application of brahe is predicting and visualizing GPS satellite orbits. The package provides built-in functions for generating 2D and 3D visualizations of satellite constellations using Plotly (Plotly Technologies Inc., 2015) and matplotlib (Hunter, 2007).

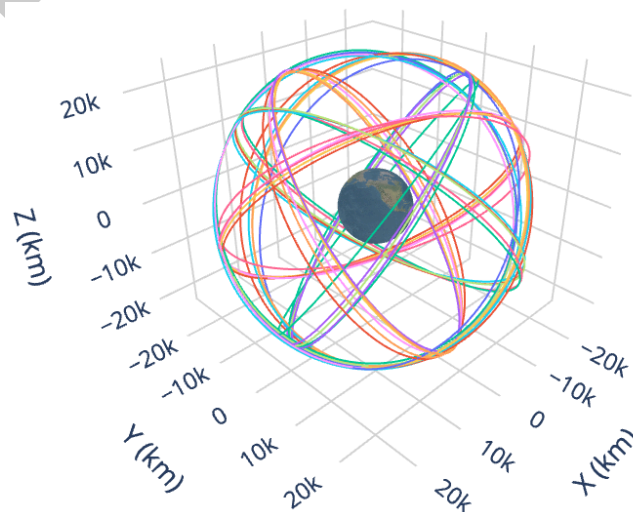


Figure 1: Visualization of all GPS Satellite Orbits

Statement of Need

While the core algorithms for predicting and modeling satellite motion have been known for decades, there is a lack of modern, open-source software that implements these algorithms in a way that is accessible to researchers and engineers. Generally, existing astrodynamics software packages have one or more barriers to entry for individuals and organizations looking to develop astrodynamics applications, and often leads to duplicated and redundant effort as researchers and engineers are forced to re-implement foundational algorithms.

Flagship commercial astrodynamics software like Systems Tool Kit (STK) ([Analytic Graphics, 2023](#)) and FreeFlyer ([a.i. Solutions, Inc., 2025](#)) are individually licensed and closed-source. The licensing costs can be prohibitive for researchers, individuals, small organizations, and start-ups. Even for larger organizations, the per-node licensing cost can make large-scale deployment prohibitive. The closed-source nature of these packages makes it difficult to understand and verify the exact algorithms and model implementations, which is critical for high-stakes applications like space mission operations ([Mars Climate Orbiter Mishap Investigation Board, 1999](#)). Major open-source projects like Orekit ([Maisonobe et al., 2010](#)) and GMAT ([Hughes et al., 2014](#)) provide extensive functionality, but are large codebases with steep learning curves, making quick-adoption and integration into projects difficult. Furthermore, Orekit is implemented in Java, which can be a barrier to adoption in the current scientific ecosystem with users who are more familiar with Python. GMAT uses a domain-specific scripting language and has limited documentation and examples, making it difficult for new users to get started. Libraries such as poliastro ([Cano Rodriguez & Martínez Garrido, 2022](#)) and Open Space Toolkit (OSTk) ([Open Space Collective, 2025](#)) provides Python interfaces, but their object-oriented architecture adds layers of abstraction that can make it difficult to adapt them to problems that outside their predefined modeling frameworks. Additionally, poliastro is no longer actively maintained and OSTk only supports Linux environments and requires a specialized Docker environment to run. Other academic tools like Basilisk ([Kenneally et al., 2020](#)), provide high-fidelity modeling capabilities for full spacecraft guidance, navigation, and control (GNC) simulations, but are not directly distributed through standard package managers like PyPI and must be compiled from source to be used. Finally, these works often have limited documentation and usage examples, making it difficult for new users to get started.

Software Design

brahe addresses these challenges by providing a modern, open-source astrodynamics library following design principles of the *Zen of Python* ([Peters, 2004](#)). We evaluated contributing to existing open-source astrodynamics libraries, but ultimately decided that the implementation choices and architecture of existing libraries made introduced too many layers of abstraction and complexity to make it easy for new users to understand, validate, or extend the core algorithms. Therefore we designed brahe from the ground-up to be modular, yet highly-composable that emphasizes simple functions that can be easily chained together to build more complex functionality. Given the breadth and complexity of astrodynamics modeling choices and, we adopt a design philosophy of “Do the Rightest Thing”—always provide a reasonable default choice for modeling decisions (e.g., time systems, reference frames, perturbation models) that is modern, current, and accurate, but allow users to override or extend these choices when needed. This allows new users to get started quickly without needing to understand all the nuances of astrodynamics modeling, while still both ensuring the correctness of their results and allowing advanced users to customize the library to their specific needs.

The core functionality is implemented in Rust for performance and safety, with Python bindings for ease-of-use and integration with the scientific Python ecosystem. brahe is provided under an MIT License to encourage adoption and facilitate integration and extensibility. To further promote adoption and aid user learning, the library is extensively documented following the Diátaxis framework ([Procida, 2024](#))—every Rust and Python function documented with types

and usage examples, there is a user guide that explains the major concepts of the library, and set of longer-form examples demonstrating how to accomplish common tasks. To maintain high code quality, the library has a comprehensive test suite for both Rust and Python. Additionally, all code samples in the documentation are automatically tested on commit to ensure they remain functional, and that the documentation accurately reflects the library's capabilities. The package testing and distribution is fully automated using GitHub Actions to run tests on multiple platforms (Linux, macOS, Windows) and Python versions (3.10+) on every code change.

Research Impact Statement

brahe has been used by current satellite missions after its adoption by aerospace companies such as Capella Space, Northwood Space, Xona Space (Reid et al., 2020), and Kongsberg Satellite Services. They have used it for mission analysis and planning, and in some cases supporting on-orbit mission operations. One particularly significant contribution is that satellite imaging prediction and task planning algorithms of Brahe were used by the first US synthetic aperture radar (SAR) satellite constellation, operated by Capella Space (Stringham et al., 2019) to predict communications and imaging opportunities. It has also been used in a number of scientific publications (Eddy et al., 2025; Kim et al., 2025). It has a small, but growing, user base in both academia and industry.

AI Usage Disclosure

The core development of brahe did not involve the use of AI tools, and in-fact, predated them. However, AI tools were used to unblock continued development in 2025 due to a breaking change in how PyO3 (the Rust-to-Python bindings library) API worked. Specifically, Claude was used to help understand the new API and refactor existing code to be compatible with the new version. Additionally, Github Copilot and Claude code were used to help implement a few long-outstanding features, specifically, the addition of trajectory data structures, numerical orbit propagators, and space weather data ingestion. AI tools have also been used to help improve test coverage and documentation. In all cases, the generated code was carefully reviewed, tested, and modified by the authors prior to merging to ensure correctness and maintainability. AI tools were not used in the writing of this paper.

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