

# Starfeeder

## Whisker Starfeeder: README

### Purpose

Manages radiofrequency identification (RFID) readers and weighing balances, and talks to a Whisker client (<http://www.whiskercontrol.com/>).

### Author/licensing

By Rudolf Cardinal. Copyright © 2015 Rudolf Cardinal. See LICENSE.txt.

### Single-folder binary distribution

Unzip the distributed file and double-click the `starfeeder` program. That's it.

### Linux source installation

*End users should opt for the single-folder binary distribution instead.*

#### Install

From a command prompt:

```
sudo apt-get install python3 python3-pip # install Python with pip
python3 -m virtualenv /PATH/TO/MY/NEW/VIRTUALENV # make a virtualenv
source /PATH/TO/MY/NEW/VIRTUALENV/bin/activate # activate the virtualenv

# pip install starfeeder --process-dependency-links # install from PyPI -- NOT YET IMPLEMENTED

cd /MY/WORKING/DIR
git clone https://egret.psychol.cam.ac.uk/git/starfeeder # Fetch code. Private for now.
pip install -e . # Install from working directory into virtualenv.
```

#### Run

```
/PATH/TO/MY/NEW/VIRTUALENV/bin/starfeeder
```

### Windows source installation

*Deprecated, as it's complex.*

#### Install

1. You need to have Python 3 installed (which will come with `pip`, `pyenv`, and sometimes `virtualenv`). Obtain it from <https://www.python.org/> and install it. We'll suppose you've installed Python at `C:\Python34`.
2. On Windows 10, install a copy of `cmake`, because PySide wants it. Also Qt. Also Git if you want to work with repositories directly. Possibly other things. (I have this working on Windows XP but not Windows 10; PySide is not building itself happily.)
3. Then fire up a Command Prompt and do:

```
C:\Python34\Tools\Scripts\pyenv.py C:\PATH\TO\MY\NEW\VIRTUALENV
C:\PATH\TO\MY\NEW\VIRTUALENV\Scripts\activate
pip install starfeeder --process-dependency-links
```

#### Run

Run the `starfeeder` program from within your virtual environment.

*Windows: just the GUI*

For normal use:

```
C:\PATH\TO\MY\NEW\VIRTUALENV\Scripts\pythonw.exe C:\PATH\TO\MY\NEW\VIRTUALENV\Scripts\starfeeder-script.py
```

*Windows: to see command-line output*

Use this for database upgrades, command-line help, and to see debugging output:

```
C:\PATH\TO\MY\NEW\VIRTUALENV\Scripts\starfeeder
```

You can append `-v` for more verbose output, or `--help` for full details.

If you use this method to run the graphical user interface (GUI) application, **do not** close the console window (this will close the GUI app).

## Changelog

### v0.1.2 (2015-12-23)

- Initial release.
- Hardware tested via Windows XP, Windows 10, and Ubuntu 14.04.

### v0.1.3 (2015-12-26)

- Ugly `moveToThread()` hack fixed by declaring `QTimer(self)` rather than `QTimer()`.
- More general updates to declare parents of `QObject` objects, except in GUI code where it just clutters things up needlessly. Note that `QLayout.addWidget()`, `QLayout.addLayout()`, and `QWidget.setLayout()` all take ownership.
- Bugfix related to using lambdas as slots (PySide causes a segmentation fault on exit <https://bugreports.qt.io/browse/PYSIDE-88>).
- Launch PDF manual as help.
- Retested with hardware on Windows XP and Linux.

### v0.1.4 (2015-12-26)

- `callback_id` set by GUI, not by derived classes of `SerialOwner`

### v0.1.5 (2016-02-27)

- bugfix to `BaseWindow.on_rfid_state()`

### v0.2.0 (2016-04-07)

- GUI log window, for PyInstaller environments.
- Uses Whisker Python library.
- Switch to Arrow datetimes internally.
- Bugfix in error handling when trying to open non-existent serial ports.

### v0.2.3 (2016-04-19) v0.2.4 (2016-04-19)

- Bugfix.

### v0.2.5

- Internal changes only?

### v0.2.6 (2016-11-24)

- Python type hints.
- NOTE that to install Python 3.4 (required for this version of PySide) under Ubuntu 16.10, you need to: - download Python 3.4.4 source, then:

```
$ tar xvf Python-3.4.4.tgz
$ cd Python-3.4.4
$ configure --enable-shared
$ make
$ sudo make install

# now unbreak wrong symlink and replace with old:
$ sudo rm /usr/bin/python3 # "make install" made this point to python3.4
$ sudo ln -s /usr/bin/python3.5 /usr/bin/python3

# now set up library links
$ sudo ln -s /usr/local/lib/libpython3.4m.so.1.0 /usr/lib/x86_64-linux-gnu/libpython3.4m.so.1.0

# this should now work:
$ python3.4
```

- Upgraded from `pyserial 3.0.1` to `3.2.1` ... also allows the use of Linux pseudoterminals for testing <http://stackoverflow.com/questions/34831131>
- Passwords obscured in debug-level database URLs.
- Top-level exception tracebacks go to `log` (like all others), not to `print()` using `traceback.print_exc()`.
- `BalanceController` could send 'ICRNOne', which is wrong; the frequency 10 Hz was offered in the dialogue, but should have been 12. Validity check added.
- Bug workaround: PROBLEM - sometimes, `WeightWhiskerTask.on_mass()` received something that was not a `MassEvent`. Not sure why (it doesn't look like anything else is ever sent); could this be a PySide signals bug?

ATTEMPT 1 - Workaround is to verify type on receipt (and complain loudly if wrong but ignore/continue). - ... no; irremediable bug in PySide (see development notes); it fails to keep references to signal parameters, so sometimes they go AWOL.

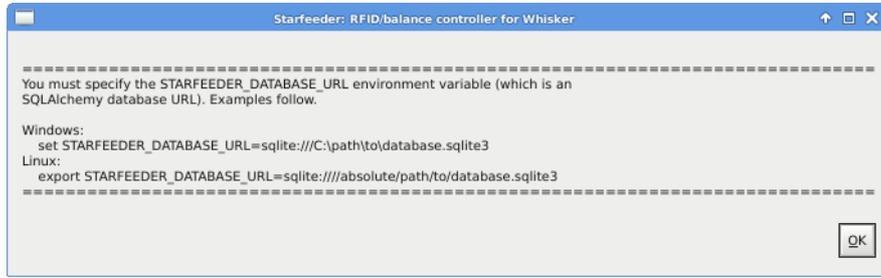
ATTEMPT 2 - Switched from PySide to PyQt5, and thus GPLv3 licensing. - Generally, this seems much better. - Even then, apparent corruption in "bytes" object passed from `SerialController.process_data()` -> `SerialController.line_received` -> [change thread] -> `RfidController.on_receive` Sometimes the received bytes object is `b"`, not what was sent. PyQt does some sort of autoconversion to C++ objects; see [http://pyqt.sourceforge.net/Docs/PyQt5/signals\\_slots.html](http://pyqt.sourceforge.net/Docs/PyQt5/signals_slots.html); and the problem appears to go away by using an encapsulating Python object... Not ideal! Does it also affect `str`? No, `str` seems OK. BUG REPRODUCED RELIABLY in `pyqt5_signal_with_bytes.py`. Reported to PyQt mailing list on 2016-12-01. SO FOR NOW: AVOID bytes OBJECTS IN PyQt5 SIGNALS.

## Installation

To install, you just unzip it and run the `starfeeder.exe` executable.

## Database setup

When you first run Starfeeder you might see this:



Before it'll work you'll also need to set an environment variable to point to a database. The simplest would be to use SQLite(<https://www.sqlite.org/>), like this:

```
set STARFEEDER_DATABASE_URL=sqlite:///C:\path\to\starfeeder_database.sqlite3
```

... and then run Sqliteman (<http://sqliteman.yarpen.cz/>) to inspect the database. But the software supports other databases (e.g. MySQL, others: <http://docs.sqlalchemy.org/en/latest/core/engines.html>) via this URL scheme. The configuration and data are stored in this database.

If the database isn't structured correctly, as it won't be if you've just invented the URL (so a blank database is autocreated), the first time you run it you get a button to "Upgrade database" (then close and re-run).



Here's the happy starting screen:



## Configuration

Configure like this:

Configure Starfeeder

**Task logic**  
 RFID effective time (s)  
 This is the time that an RFID event 'persists' for:

**Whisker**  
 Whisker server:   
 Whisker port:   
 Whisker client message prefix:

**RFID readers**

rfid0: /dev/ttyUSB0, 9600 8N1, no flow control

**Balances**

balance0: /dev/ttyUSB1, 9600 8E1, XON/OFF

Configure RFID reader

**Enabled**  
 Device ID (set when first saved) 1

RFID name:

**Once created and used for real data, AVOID RENAMING devices; RFID/mass data will refer to these entries by number (not name).**  
**NOTE:** the intended RFID devices are fixed in hardware to 9600 bps, 8N1

**Serial port settings**

Serial port:

Speed in bits per second:

**Data bits**  
 8

**Parity bit**  
 None

**Stop bits**  
 1

**Flow control**

None (not advised)  
 XON/XOFF software flow control  
 RTS/CTS hardware flow control  
 DTR/DSR hardware flow control

*I am not completely sure if the RFID reader supports any flow control. Under Linux, XON/XOFF and RTS/CTS don't break it (but that doesn't mean it uses them). Under Windows, RTS/CTS breaks it. The physical serial interface inside it is RS-485, which is two-wire and therefore not only can't have RTS/CTS but is unidirectional. I don't know if the USB interface adds anything; I suspect not. So the best option is either XON/XOFF or None – probably None.*

**Configure balance**

**Enabled**

**Once created and used for real data, AVOID RENAMING devices; RFID/mass data will refer to these entries by number (not name).**

Device ID (set when first saved) 1

Balance name:

Paired RFID reader:

**Measurement settings**

Amplifier signal filter (ASF) mode (0 = none; see p37 of manual):

Fast response filter (FMD; see p37 of manual):

Measurement rate (Hz):

Number of consecutive readings judged for stability:

Stability tolerance (kg) (range [max - min] of consecutive readings must not exceed this):

Minimum mass for detection (kg):

Mass below which balance will unlock (kg):

Reference (calibration) mass (kg):

Zero (tare) calibration point:

Reference mass calibration point:

Read continuously (inefficient):

**NOTE:** the intended balance devices default to 9600 bps, 8E1, and are restricted in their serial options

**Serial port settings**

Serial port:

Speed in bits per second:

**Data bits**

8

**Parity bit**

None  Even

**Stop bits**

1

**Flow control**

None (not advised)

XON/XOFF software flow control

The balance says (p15 of its manual) that it copes with XON/XOFF.

When you click "Start..." it starts the RFID readers, balances, and connects to Whisker.

## Data storage and output

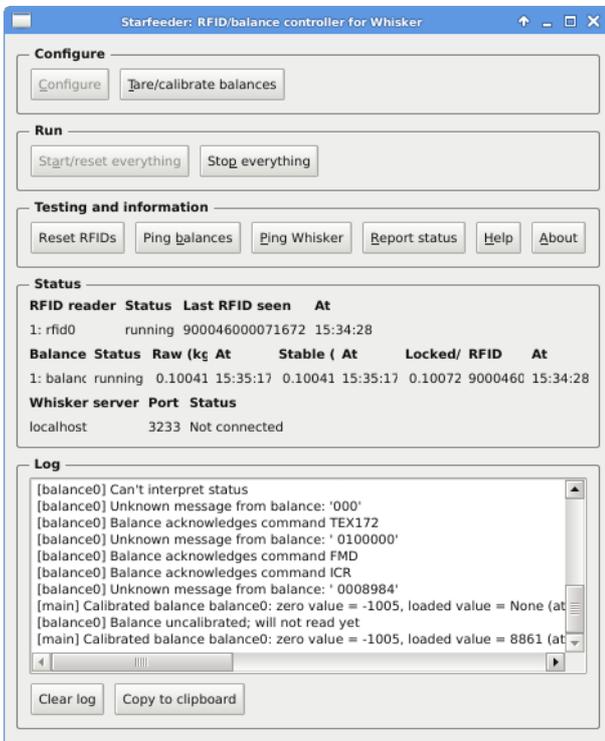
All data goes to the database (as well as to Whisker if connected).

The balance won't produce numbers until it's tared and calibrated. The default is for an 0.1kg calibration mass, so you just start; click the Tare/calibrate button; then remove all mass and click "Tare", then put the 0.1kg mass on and click "Calibrate 0.1kg". It'll store the readings so you don't necessarily have to recalibrate next time.

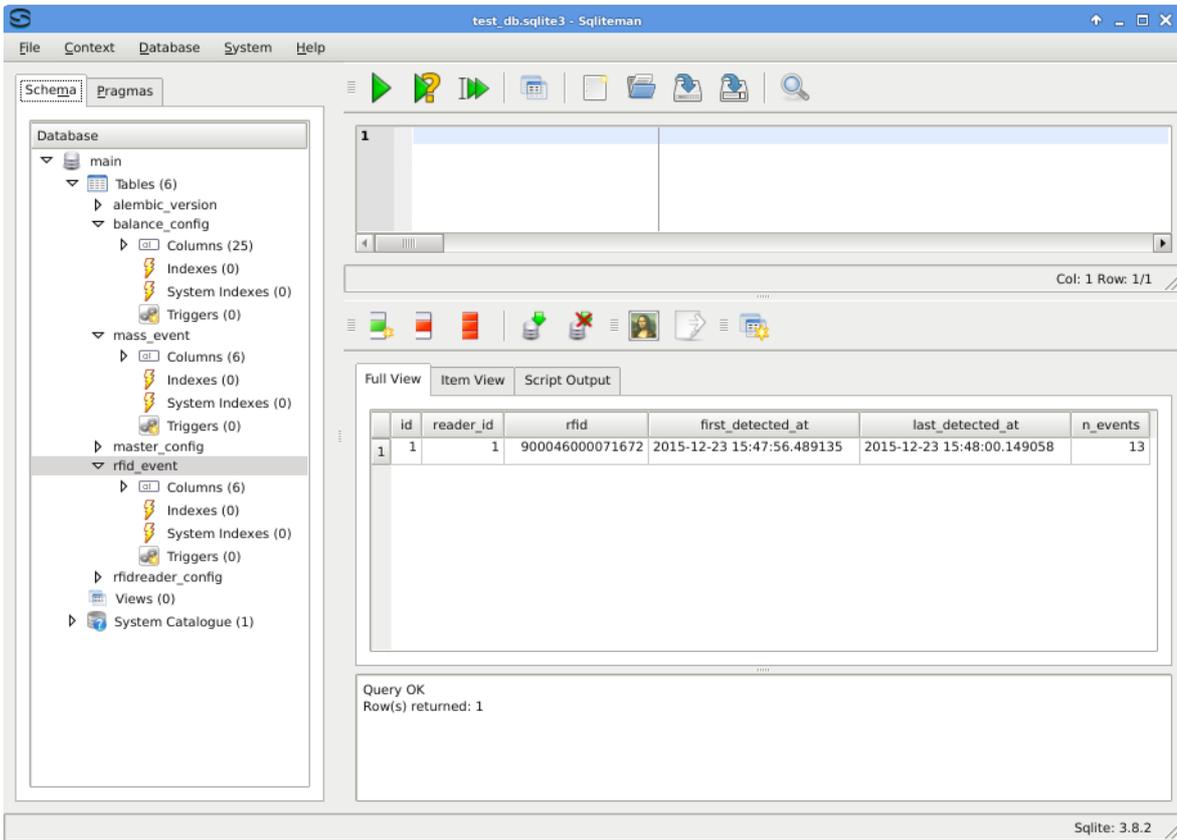
**Calibrate balances**

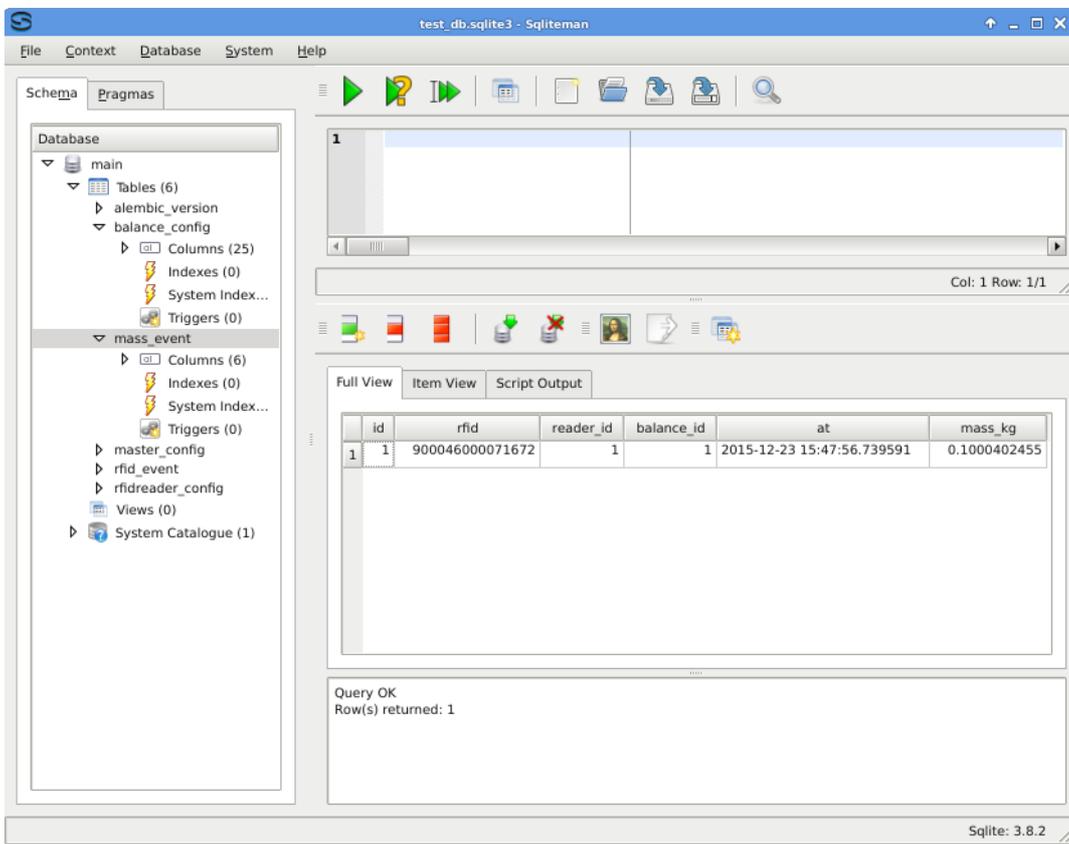
Balance 1:

When it's running and things are happening, it looks like this:

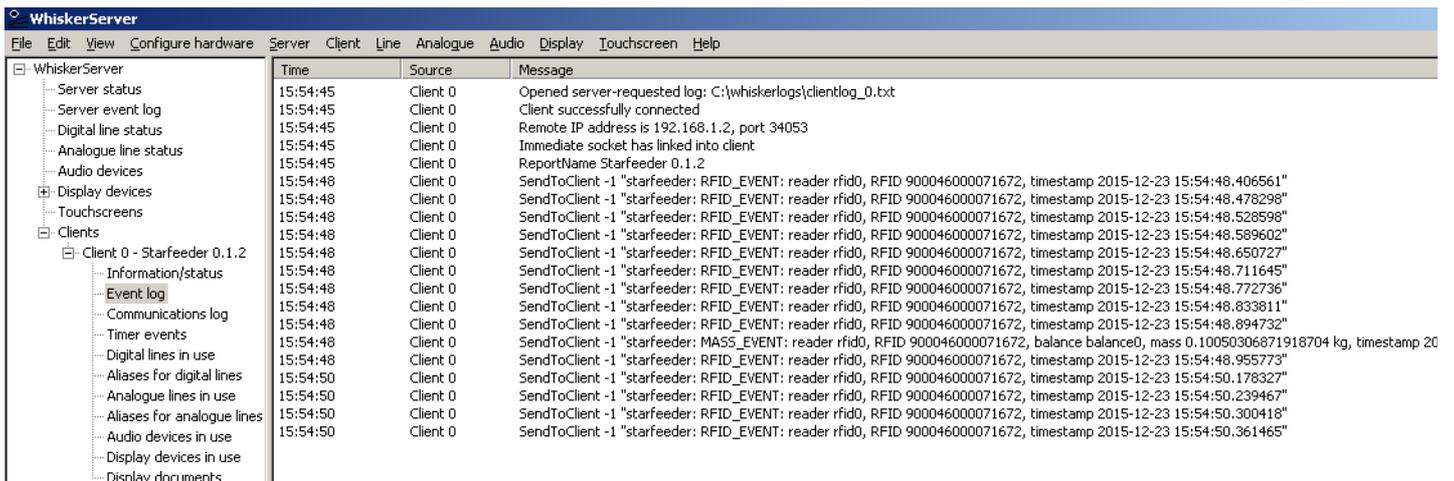


Here are some examples of the output, as seen by Sqliteman:





... and by Whisker:



## Operating systems tested

- Linux (Ubuntu 14.04)
- Windows XP
- Windows 10

## Troubleshooting

On Windows:

- Download and install PuTTY (<http://www.chiark.greenend.org.uk/~sgtatham/putty/>); this is a good terminal emulator (as well as an excellent SSH client).

On Linux:

- Lots of ways. But using PySerial (as Starfeeder does):

```
pip install https://github.com/pyserial/pyserial/tarball/3e02f7052747521a21723a618dccc303065da732 # install PySerial 3.0b1
python -m serial.tools.miniterm /dev/ttyUSB0 9600 --eol LF --develop --parity N # RFID reader
python -m serial.tools.miniterm /dev/ttyUSB1 9600 --eol LF --develop --parity E # Balance
```

Regardless of operating system:

- For the RFID readers:

- Connect to the correct COM port using the settings 9600, 8N1, XON/XOFF (do not use RTS/CTS under Windows).
- A few key commands are shown below.
- Note that the commands are case-sensitive and single-character only (do not send a newline or you will cancel ongoing reads).
- If it doesn't understand something, it will say "?".

| Action        | You type | Reply   |
|---------------|----------|---|
| Reset         | x        | MULTITAG-125 01                                   |
| Start reading | c        | nothing, then RFID tag codes as they are detected |
| Stop reading  | p        | s   |

- For the balance:
  - Connect to the correct COM port using the settings 9600, **8E1**, XON/XOFF.
  - The balance is particularly frustrating, as it usually doesn't say anything if you get the syntax wrong. Occasionally it says:.
  - Specimen commands are shown below.

| Action               | You type | Reply   |
|----------------------|----------|---------|
| Restart              | RES;     | nothing |
| Request status       | ESR?;    | 000     |
| Request ASCII output | COF3;    | 0       |
| Request 10 readings  | MSV?10;  | data    |