

# Tools to Calculate Adiabatic Invariants from Dynamic Simulations of Earth's Magnetosphere

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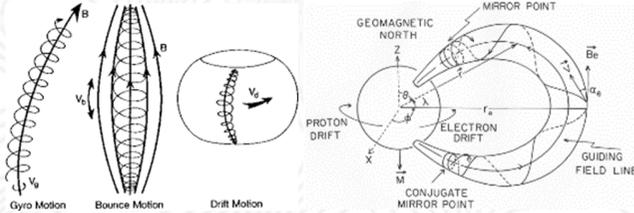
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## Introduction: Adiabatic Invariants

Trapped Particles in Magnetospheres undergo three periodic motions, each with their own characterizing invariant parameter (variable in parenthesis).

1. Gyration around a field line ( $\mu$ )
2. Bounce motion along a field line ( $K$ )
3. Drift azimuthally around the magnetized body ( $L^*$ )



- Phase space density  $f(\vec{v}, \vec{x})$  can recast in terms  $f(\mu, K, L^*, \phi_\mu, \phi_K, \phi_{L^*})$
- When put in this form  $f$  will remain constant during slow-changing (slower than drift period time scale) reconfigurations of the global magnetic field when no work is done
- This property is essential for studying the dynamics of trapped particles during geomagnetic storms

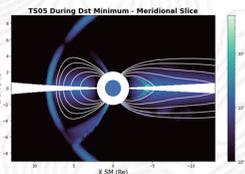
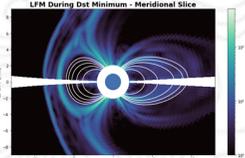
## Calculation from Dynamic Simulations

The calculation requires a global magnetic field model. Existing practices use empirical magnetic models:

- Tsyganenko (T96-TS05), Olson & Pfizter (Quiet / Dynamic), Alexeev, Ostapenko & Maltsev, Mead & Fairfield, and more

We argue there is an advantage to being able to use magnetic fields from simulations:

1. Empirical models don't capture fine current structures like MHD models do (see right plots: LFM-RCM at top is MHD and TS05 below is empirical)
2. Studies which guide test particles through simulation fields should always use the simulation fields for maximal self-consistency



## Algorithm for Gyration Invariant $\mu$

No special algorithm is required for calculation of  $\mu$ , because it does not require global magnetic field knowledge. The relativistic equation is given by:

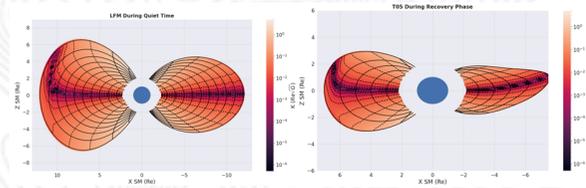
$$\mu = \frac{p^2}{2m_0 B}$$

## Algorithm for Bounce Motion Invariant $K$

- Algorithm uses native simulation grid
- Traces field along bounce path using Runge-Kutta 45
- Takes subset of field line trace between mirroring magnetic field intensities ( $B_m$ ). This is the bounce path.
- Once bounce path is determined, numerically integrate:

$$K = \int_{s_1}^{s_2} \sqrt{B_m - B(s)} ds$$

Plot below shows  $K$  for particles mirroring at varying magnetic latitudes in the LFM and TS05 models (SM coordinates) ↓



## Algorithm for Drift Shell Invariant $L^*$

- Iterate over  $N_{MLT}$  equally spaced local times
  1. Use a linear search for field line at increasing/decreasing radii to find field line conserves  $K(B_m)$
  2. First advance in large steps, then backtrack and take small steps if gone too far
- Once drift shell is determined, use numerical integration with spline smoothing over polar cap (Stokes simplification)

Basic Equation:

$$L^* = \frac{2\pi B_E R_E^2}{\iint \vec{B} \cdot \hat{n} ds}$$



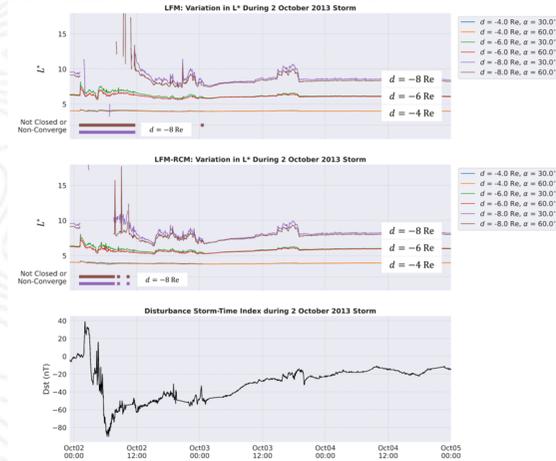
Stokes Simplification (at Model Inner Boundary):

$$L^* = \left( \frac{R_{in}}{R_E} \right) \frac{2\pi}{\int_0^{2\pi} \sin^2(\theta(\phi)) d\phi}$$

## Comparison of Results from LFM Simulations during Geomagnetic Storm

Calculated adiabatic invariants during 2 October 2013 geomagnetic storm

- Calculated at fixed points with fixed local pitch angles
- Calculation can be parallelized over time
- Biggest deviations in  $L^*$  from dipole  $L^*$  ( $L = L^*$ ) occur farther into the magnetosphere where the external field holds greater influence
- Differences between models in the duration of non-closed / non-convergent drift shells during main phase of storm
- Different in structure of  $L^*$  during early recovery phase



## Analysis of Phase Space Density with RBSP Data

Previously established observational techniques tracks time evolution of  $f(L^*)$  at fixed  $\mu, K$  to investigate energization processes (Green et al., 2004)

- $f(L^*)$  reflects a truer "state variable" during storms than  $f(L)$
- Different processes will distort the  $f(L^*)$  curve over time; such as radial diffusion (top left →) and internal acceleration (top right →)
- Curve be calculated from instruments measuring flux  $j(\alpha, E)$  such as RBSP

Method:

- Interpolate flux distribution at  $\alpha/E$  corresponding to fixed  $\mu/K$
- Compute  $L^*$  corresponding to  $K$  and ephemeris location

Example (bottom right →) shows combination of radial diffusion and precipitation loss

