

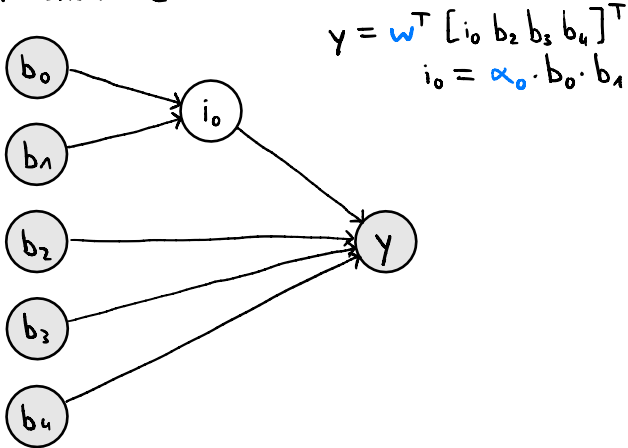


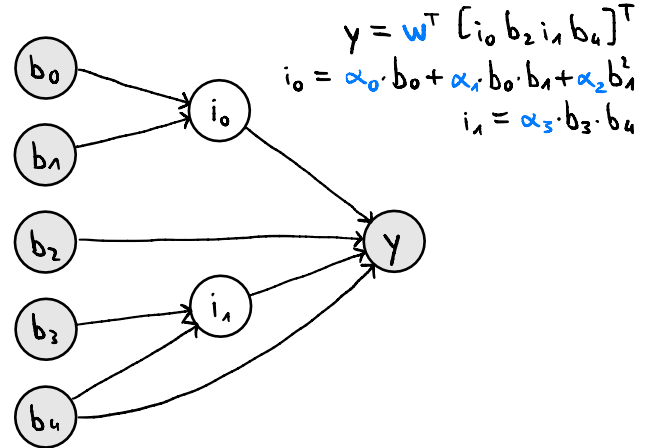
Interaction Datasets

observed node , unobserved node , target y , base features b_n , interactions i_j , causes c_k
all root nodes (b_n or c_k) sampled uniformly from $[0, 1]$, everything with Gaussian noise $\mathcal{N}(0, \sigma^2 = 0.1)$

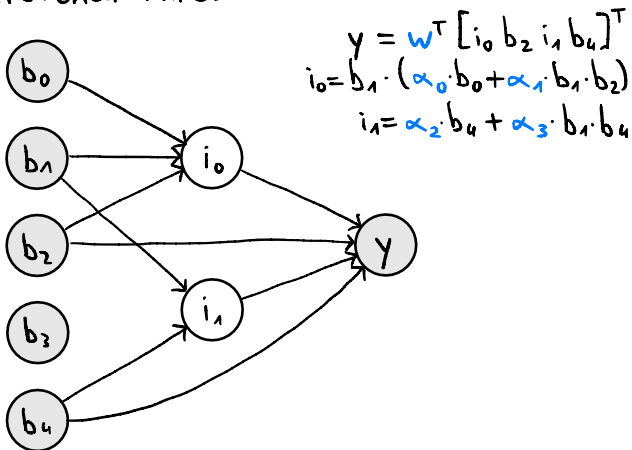
Interaction One



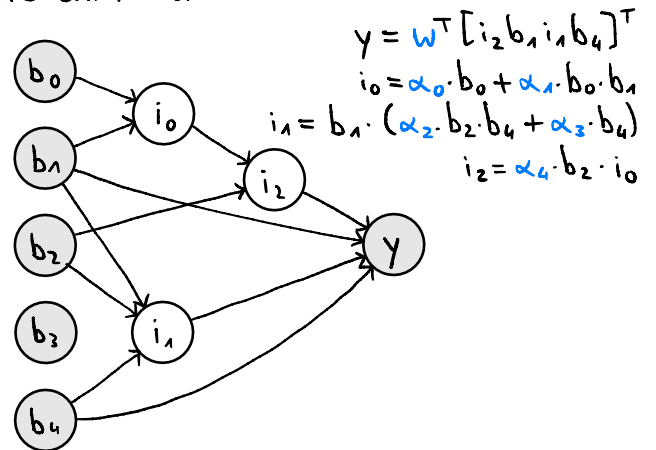
Interaction Two



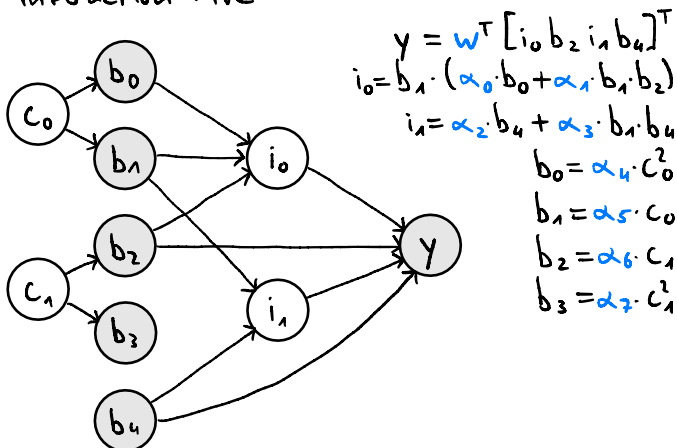
Interaction Three



Interaction Four



Interaction Five



Interaction Six

