

ACT-R – subsymbolic parameters

Base-level learning

Switched on by `subsymbolic=True`.

The equation describing learning of base-level activation for a chunk i is:

$$B_i = \ln\left(\sum_{j=1}^n (t_j^{-d})\right) + \eta$$

- n : The number of presentations for chunk i
- t_j : The time since the j th presentation
- d : The decay parameter (set by `decay`)
- η : the instantaneous noise

The (instantaneous) noise:

$$\sigma^2 = s^2 * \pi^2 / 3$$

- s : The noise parameter (set by `instantaneous_noise`)

Retrieval latency:

$$T = F e^{-A}$$

- A : Activation of the chunk retrieved
- F : The latency parameter (set by `latency_parameter`)

Retrieval latency when retrieval fails:

$$T = F e^{-\tau}$$

- τ : The retrieval threshold (set by `retrieval_threshold`)
- F : The latency parameter (set by `latency_parameter`)

For an example see `u4_paired` in **tutorials**.

Source and activation

Switched on by `subsymbolic=True` and specifying `buffer_spreading_activation` (see below).

$$A_i = B_i + \sum_k \sum_j W_{kj} * S_{ji}$$

- A_i : activation of the chunk i
- B_i : base-level activation, see above
- W_{kj} : the amount of activation from source j in buffer k
- S_{ji} : the strength of association from source j to chunk i

W_{kj} is set by `buffer_spreading_activation`. The value of this parameter is a dictionary in which keys specify what buffers should be used for spreading activations, values specify the amount of activation in these buffers.

$$S_{ji} = S - \ln(fan_j)$$

- S : the maximum associative strength (set by `strength_of_association`)
- fan_j : the number of chunks in declarative memory in which j is the value of a slot plus one for chunk j being associated with itself

For an example see `u5_fan` in **tutorials**.

Adding partial matching

Switched on by `subsymbolic=True` and `partial_matching=True`.

$$A_i = B_i + \sum_k \sum_j W_{kj} * S_{ji} + \sum_l M_{li}$$

- M_{li} : The similarity between the value l in the retrieval specification and the value in the corresponding slot of chunk i

The similarity currently only uses default values - a maximum similarity (0) and a maximum different (-1). To be added: let the modeler set these values. For an example see `u5_grouped` in **tutorials**.

Utility in production rules

Switched on by `partial_matching=True`. The (utility) noise:

$$\sigma^2 = s^2 * \pi^2/3$$

- *s*: The noise parameter (set by `utility_noise`)

Each rule can specify its own utility (by having the parameter `utility=n`, where *n* is a number). Each rule can also specify reward it creates for utility learning (by having the parameter `reward=n`, where *n* is a number). Utility learning is set by `utility_learning=True`. The learning rate for utility learning is set by `utility_alpha`. For an example see `u6_simple` in **tutorials**.